



CS M146 Discussion: Week 6 (Add-on) PyTorch Introduction and Tutorial

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PYTÖRCH

It's a Python-based scientific computing package

A replacement for NumPy to use the power of GPUs A deep learning research platform that provides maximum flexibility and speed





Three Levels of Abstraction

- **Tensor:** Imperative ndarray but runs on GPU
- **Variable:** Node in a computational graph; stores data and gradient
- **Module:** A neural network layer; may store state or learnable weights

Credit:

https://web.cs.ucdavis.edu/~yjlee/teaching/ecs289g-winter2018/Pytorch_Tutorial.pdf

- PyTorch Tensors are just like numpy arrays, but they can run on GPU.
- No built-in notion of computational graph, or gradients, or deep learning.
- Here we fit a two-layer net using PyTorch Tensors.

```
import torch
dtype = torch.FloatTensor
N, D in, H, D out = 64, 1000, 100, 10
x = torch.randn(N, D in).type(dtype)
y = torch.randn(N, D_out).type(dtype)
w1 = torch.randn(D in, H).type(dtype)
w2 = torch.randn(H, D out).type(dtype)
learning rate = 1e-6
for t in range(500):
    h = x.mm(w1)
    h relu = h.clamp(min=0)
    y \text{ pred} = h \text{ relu.mm}(w2)
    loss = (y pred - y).pow(2).sum()
    grad y pred = 2.0 * (y \text{ pred} - y)
    grad w2 = h relu.t().mm(grad y pred)
    grad h relu = grad y pred.mm(w2.t())
    grad h = grad h relu.clone()
    grad h[h < 0] = 0
    grad w1 = x.t().mm(grad h)
    w1 -= learning rate * grad w1
    w2 -= learning rate * grad w2
```

Create random tensors for data and

weights

```
import torch
```

dtype = torch.FloatTensor

```
N, D_in, H, D_out = 64, 1000, 100, 10
x = torch.randn(N, D_in).type(dtype)
y = torch.randn(N, D_out).type(dtype)
w1 = torch.randn(D_in, H).type(dtype)
w2 = torch.randn(H, D_out).type(dtype)
```

```
learning rate = 1e-6
for t in range(500):
    h = x.mm(w1)
    h relu = h.clamp(min=0)
    y \text{ pred} = h \text{ relu.mm}(w2)
    loss = (y pred - y).pow(2).sum()
    grad y pred = 2.0 * (y \text{ pred} - y)
    grad w2 = h relu.t().mm(grad_y_pred)
    grad h relu = grad y pred.mm(w2.t())
    grad h = grad h relu.clone()
    grad h[h < 0] = 0
    grad w1 = x.t().mm(grad h)
    w1 -= learning rate * grad w1
```

w2 -= learning rate * grad w2

Forward pass: compute predictions

and loss

```
import torch
dtype = torch.FloatTensor
N, D in, H, D out = 64, 1000, 100, 10
x = torch.randn(N, D in).type(dtype)
y = torch.randn(N, D out).type(dtype)
w1 = torch.randn(D_in, H).type(dtype)
w2 = torch.randn(H, D out).type(dtype)
learning rate = 1e-6
for t in range(500):
    h = x.mm(w1)
    h relu = h.clamp(min=0)
    y \text{ pred} = h \text{ relu.mm}(w2)
    loss = (y pred - y).pow(2).sum()
    grad y pred = 2.0 * (y \text{ pred} - y)
```

```
grad_y_pred = 2.0 * (y_pred - y)
grad_w2 = h_relu.t().mm(grad_y_pred)
grad_h_relu = grad_y_pred.mm(w2.t())
grad_h = grad_h_relu.clone()
grad_h[h < 0] = 0
grad_w1 = x.t().mm(grad_h)
w1 -= learning_rate * grad_w1
w2 -= learning_rate * grad_w2</pre>
```

Backward pass: manually compute

gradients

```
import torch
dtype = torch.FloatTensor
N, D in, H, D out = 64, 1000, 100, 10
x = torch.randn(N, D in).type(dtype)
y = torch.randn(N, D_out).type(dtype)
w1 = torch.randn(D_in, H).type(dtype)
w2 = torch.randn(H, D_out).type(dtype)
learning rate = 1e-6
for t in range(500):
    h = x.mm(w1)
    h relu = h.clamp(min=0)
    y \text{ pred} = h \text{ relu.mm}(w2)
    loss = (y pred - y).pow(2).sum()
    grad y pred = 2.0 * (y \text{ pred} - y)
```

```
grad_w2 = h_relu.t().mm(grad_y_pred)
grad_h_relu = grad_y_pred.mm(w2.t())
grad_h = grad_h_relu.clone()
grad_h[h < 0] = 0
grad_w1 = x.t().mm(grad_h)</pre>
```

```
w1 -= learning_rate * grad_w1
w2 -= learning_rate * grad_w2
```

Gradient descent step on weights

```
import torch
dtype = torch.FloatTensor
N, D in, H, D out = 64, 1000, 100, 10
x = torch.randn(N, D in).type(dtype)
y = torch.randn(N, D_out).type(dtype)
w1 = torch.randn(D in, H).type(dtype)
w2 = torch.randn(H, D out).type(dtype)
learning rate = 1e-6
for t in range(500):
    h = x.mm(w1)
    h relu = h.clamp(min=0)
    y \text{ pred} = h \text{ relu.mm}(w2)
    loss = (y pred - y).pow(2).sum()
    grad y pred = 2.0 * (y \text{ pred} - y)
    grad w2 = h relu.t().mm(grad y pred)
    grad h relu = grad y pred.mm(w2.t())
    grad h = grad h relu.clone()
    \operatorname{grad} h[h < 0] = 0
    grad_w1 = x.t().mm(grad_h)
    w1 -= learning rate * grad w1
    w2 -= learning rate * grad w2
```

To run on GPU, just cast tensors to a cuda datatype! *(Optional)*

```
import torch
```

dtype = torch.cuda.FloatTensor

```
N, D_in, H, D_out = 64, 1000, 100, 10
x = torch.randn(N, D_in).type(dtype)
y = torch.randn(N, D_out).type(dtype)
w1 = torch.randn(D_in, H).type(dtype)
w2 = torch.randn(H, D_out).type(dtype)
```

```
learning_rate = 1e-6
for t in range(500):
    h = x.mm(w1)
    h_relu = h.clamp(min=0)
    y_pred = h_relu.mm(w2)
    loss = (y_pred - y).pow(2).sum()
```

```
grad_y_pred = 2.0 * (y_pred - y)
grad_w2 = h_relu.t().mm(grad_y_pred)
grad_h_relu = grad_y_pred.mm(w2.t())
grad_h = grad_h_relu.clone()
grad_h[h < 0] = 0
grad_w1 = x.t().mm(grad_h)
w1 -= learning_rate * grad_w1
w2 -= learning_rate * grad_w2</pre>
```

A PyTorch **Variable** is a node in a computational graph

x.data is a Tensor

x.grad is a Variable of gradients (same shape as x.data)

x.grad.data is a Tensor of gradients

import torch
from torch.autograd import Variable

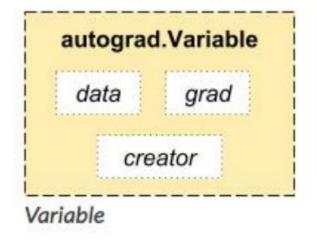
```
N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D_out), requires_grad=True)
```

```
learning_rate = 1e-6
for t in range(500):
    y_pred = x.mm(w1).clamp(min=0).mm(w2)
    loss = (y_pred - y).pow(2).sum()
    if w1.grad: w1.grad.data.zero_()
    if w2.grad: w2.grad.data.zero_()
    loss.backward()
    w1.data -= learning_rate * w1.grad.data
    w2.data -= learning_rate * w2.grad.data
```

The autograd package provides automatic differentiation for all operations on Tensors.

autograd.Variable is the central class of the package. It wraps a Tensor, and supports nearly all of operations defined on it.

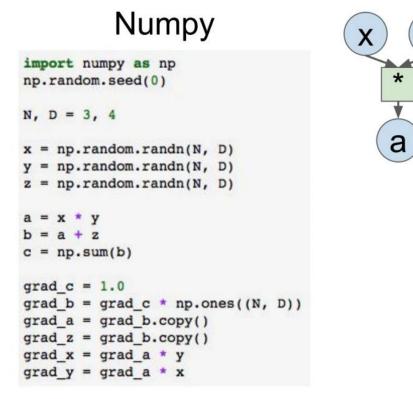
Once you finish your computation you can call .backward() and have all the gradients computed automatically.



Ζ

b

С



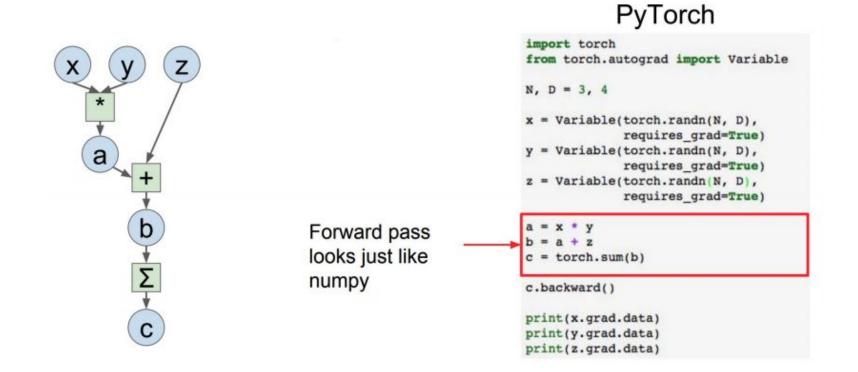
X Ζ * а b С

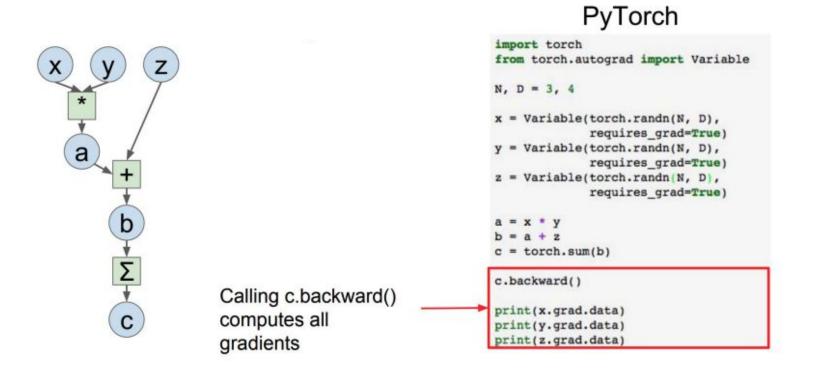
Define **Variables** to start building a computational graph

PyTorch

```
a = x * y
b = a + z
c = torch.sum(b)
c.backward()
print(x.grad.data)
print(y.grad.data)
```

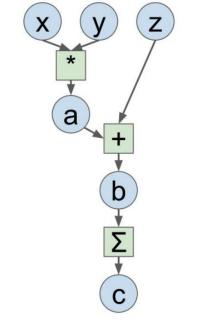
```
print(z.grad.data)
```





import torch from torch.autograd import Variable N, D = 3, 4x = Variable(torch.randn(N, D).cuda(), Run on GPU by requires grad=True) Variable(torch.randn(N, D).cuda(), casting to .cuda() requires grad=True) z = Variable(torch.randn(N, D).cuda(), requires grad=True) = x * v = a + z c = torch.sum(b)c.backward() print(x.grad.data) print(y.grad.data) print(z.grad.data)

PyTorch



PyTorch Tensors and Variables Have the same API!

Variables remember how they were created (for backprop)

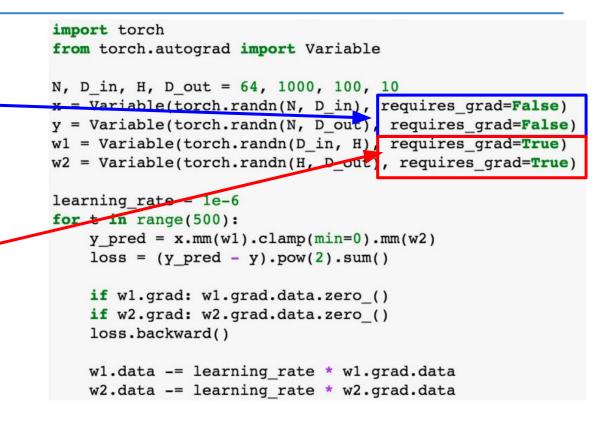
import torch
from torch.autograd import Variable

```
N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D_out), requires_grad=True)
```

```
learning_rate = 1e-6
for t in range(500):
    y_pred = x.mm(w1).clamp(min=0).mm(w2)
    loss = (y_pred - y).pow(2).sum()
    if w1.grad: w1.grad.data.zero_()
    if w2.grad: w2.grad.data.zero_()
    loss.backward()
    w1.data -= learning_rate * w1.grad.data
    w2.data -= learning_rate * w2.grad.data
```

We will not want gradients (of loss) with respect to data

Do want gradients with respect to weights



Forward pass looks exactly the same as the Tensor version, but everything is a Variable now

```
import torch
from torch.autograd import Variable
```

```
N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D_out), requires_grad=True)
```

```
learning_rate = 1e-6
for t in range(500):
    y_pred = x.mm(w1).clamp(min=0).mm(w2)
    loss = (y_pred - y).pow(2).sum()
```

```
if w1.grad: w1.grad.data.zero_()
if w2.grad: w2.grad.data.zero_()
loss.backward()
```

```
w1.data -= learning_rate * w1.grad.data
w2.data -= learning_rate * w2.grad.data
```

Compute gradient of loss with respect to w1 and w2 (zero out grads first)

```
import torch
from torch.autograd import Variable
```

```
N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D out), requires grad=True)
```

```
learning_rate = 1e-6
for t in range(500):
    y_pred = x.mm(w1).clamp(min=0).mm(w2)
    loss = (y_pred - y).pow(2).sum()
```

```
if w1.grad: w1.grad.data.zero_()
if w2.grad: w2.grad.data.zero_()
loss.backward()
```

```
w1.data -= learning_rate * w1.grad.data
w2.data -= learning rate * w2.grad.data
```

Make gradient step on weights

```
import torch
from torch.autograd import Variable
N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D out), requires grad=True)
```

```
learning_rate = 1e-6
for t in range(500):
    y_pred = x.mm(w1).clamp(min=0).mm(w2)
    loss = (y_pred - y).pow(2).sum()
```

```
if w1.grad: w1.grad.data.zero_()
if w2.grad: w2.grad.data.zero_()
loss.backward()
```

```
w1.data -= learning_rate * w1.grad.data
w2.data -= learning_rate * w2.grad.data
```

PyTorch: New Autograd Functions

Define your own autograd functions by writing forward and backward for Tensors class ReLU(torch.autograd.Function):
 def forward(self, x):
 self.save_for_backward(x)
 return x.clamp(min=0)

def backward(self, grad_y):
 x, = self.saved_tensors
 grad_input = grad_y.clone()
 grad_input[x < 0] = 0
 return grad_input</pre>

PyTorch: New Autograd Functions

```
class ReLU(torch.autograd.Function):
    def forward(self, x):
        self.save_for_backward(x)
        return x.clamp(min=0)
```

```
def backward(self, grad_y):
    x, = self.saved_tensors
    grad_input = grad_y.clone()
    grad_input[x < 0] = 0
    return grad input</pre>
```

Can use our new autograd function in the forward pass

```
N, D_in, H, D_out = 64, 1000, 100, 10
```

```
x = Variable(torch.randn(N, D_in), requires_grad=False)
y = Variable(torch.randn(N, D_out), requires_grad=False)
w1 = Variable(torch.randn(D_in, H), requires_grad=True)
w2 = Variable(torch.randn(H, D out), requires grad=True)
```

```
learning_rate = 1e-6
for t in range(500):
    relu = ReLU()
    y_pred = relu(x.mm(w1)).mm(w2)
    loss = (y pred - y).pow(2).sum()
```

```
if w1.grad: w1.grad.data.zero_()
if w2.grad: w2.grad.data.zero_()
loss.backward()
```

```
w1.data -= learning_rate * w1.grad.data
w2.data -= learning_rate * w2.grad.data
```

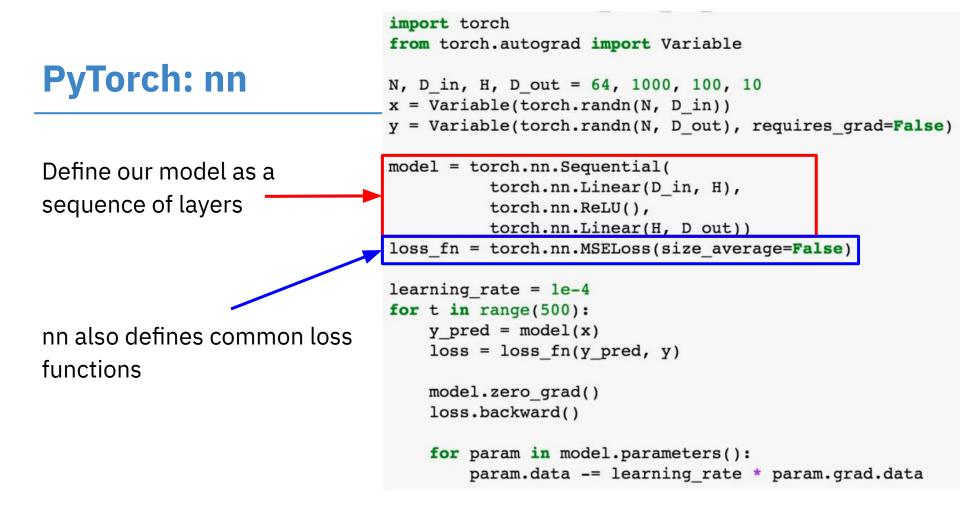
Higher-level wrapper for working with neural nets

Similar to Keras and friends ...

but only one, and it's good =)

```
import torch
from torch.autograd import Variable
N, D in, H, D out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D in))
y = Variable(torch.randn(N, D out), requires grad=False)
model = torch.nn.Sequential(
          torch.nn.Linear(D in, H),
          torch.nn.ReLU(),
          torch.nn.Linear(H, D out))
loss fn = torch.nn.MSELoss(size average=False)
learning rate = 1e-4
for t in range(500):
    y \text{ pred} = \text{model}(x)
    loss = loss fn(y pred, y)
    model.zero grad()
    loss.backward()
```

```
for param in model.parameters():
    param.data -= learning_rate * param.grad.data
```



Forward pass:

feed data to model, and

prediction to loss function

```
import torch
from torch.autograd import Variable
```

```
N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)
```

```
learning_rate = 1e-4
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)
```

```
model.zero_grad()
loss.backward()
for param in model.parameters():
    param.data -= learning_rate * param.grad.data
```

Backward pass:

compute all gradients

```
import torch
from torch.autograd import Variable
N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)
model = torch.nn.Sequential(
        torch.nn.Linear(D_in, H),
        torch.nn.ReLU(),
        torch.nn.Linear(H, D_out))
loss_fn = torch.nn.MSELoss(size_average=False)
```

```
learning_rate = 1e-4
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)
```

model.zero_grad()
loss.backward()

```
for param in model.parameters():
    param.data -= learning_rate * param.grad.data
```

Make gradient step on each

model parameter

import torch
from torch.autograd import Variable

```
N, D_in, H, D_out = 64, 1000, 100, 10
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)
```

```
learning_rate = 1e-4
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)
    model.zero_grad()
    loss.backward()
```

for param in model.parameters():
 param.data -= learning rate * param.grad.data

PyTorch: optim

Use an optimizer for different

update rules

import torch
from torch.autograd import Variable
N, D in, H, D out = 64, 1000, 100, 10

```
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)
```

learning rate = 1e-4

```
pred = model(x)
loss = loss_fn(y_pred, y)
optimizer.zero_grad()
loss.backward()
```

```
optimizer.step()
```

PyTorch: optim

Update all the parameters

after computing gradients

import torch
from torch.autograd import Variable

```
N, D_{in}, H, D_{out} = 64, 1000, 100, 10
```

```
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)
```

```
for t in range(500):
    y_pred = model(x)
    loss = loss_fn(y_pred, y)
```

```
optimizer.zero_grad()
loss.backward()
```

optimizer.step()

A Pytorch **Module** is a neural net layer; it inputs and outputs Variables

Modules can contain weights (as Variables) or other Modules

You can define your own Modules using autograd!

import torch
from torch.autograd import Variable

```
class TwoLayerNet(torch.nn.Module):
    def __init__(self, D_in, H, D_out):
        super(TwoLayerNet, self).__init__()
        self.linear1 = torch.nn.Linear(D_in, H)
        self.linear2 = torch.nn.Linear(H, D_out)
```

```
def forward(self, x):
    h_relu = self.linear1(x).clamp(min=0)
    y_pred = self.linear2(h_relu)
    return y_pred
```

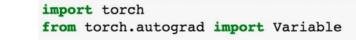
```
N, D_in, H, D_out = 64, 1000, 100, 10
```

```
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)
```

```
model = TwoLayerNet(D_in, H, D_out)
```

```
criterion = torch.nn.MSELoss(size_average=False)
optimizer = torch.optim.SGD(model.parameters(), lr=1e-4)
for t in range(500):
    y_pred = model(x)
    loss = criterion(y_pred, y)
    optimizer.zero_grad()
    loss.backward()
```

```
optimizer.step()
```





Define new modules

Define our whole model as a single module

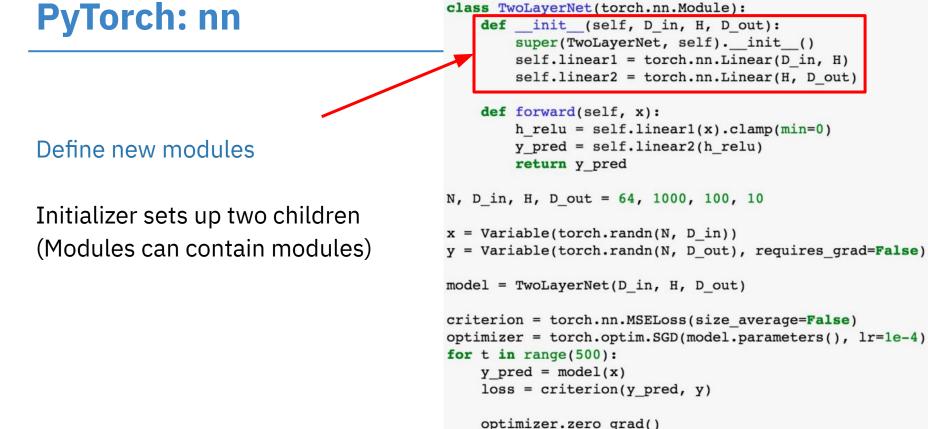
```
class TwoLayerNet(torch.nn.Module):
    def __init__(self, D_in, H, D_out):
        super(TwoLayerNet, self).__init__()
        self.linear1 = torch.nn.Linear(D_in, H)
        self.linear2 = torch.nn.Linear(H, D_out)
    def forward(self, x):
        h_relu = self.linear1(x).clamp(min=0)
        y_pred = self.linear2(h_relu)
        return y_pred
```

```
N, D_in, H, D_out = 64, 1000, 100, 10
```

```
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)
model = TwoLayerNet(D in, H, D out)
```

```
criterion = torch.nn.MSELoss(size_average=False)
optimizer = torch.optim.SGD(model.parameters(), lr=1e-4)
for t in range(500):
    y_pred = model(x)
    loss = criterion(y_pred, y)
    optimizer.zero_grad()
    loss.backward()
    optimizer.step()
```

import torch
from torch.autograd import Variable



```
loss.backward()
optimizer.step()
```

Define new modules

Define forward pass using child modules and autograd ops on Variables

No need to define backward autograd will handle it import torch
from torch.autograd import Variable

```
class TwoLayerNet(torch.nn.Module):
    def __init__(self, D_in, H, D_out):
        super(TwoLayerNet, self).__init__()
        self.linear1 = torch.nn.Linear(D_in, H)
        self.linear2 = torch.nn.Linear(H, D_out)
```

```
def forward(self, x):
    h_relu = self.linear1(x).clamp(min=0)
    y_pred = self.linear2(h_relu)
    return y_pred
```

```
N, D_in, H, D_out = 64, 1000, 100, 10
```

```
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D out), requires grad=False)
```

```
model = TwoLayerNet(D_in, H, D_out)
```

optimizer.step()

```
criterion = torch.nn.MSELoss(size_average=False)
optimizer = torch.optim.SGD(model.parameters(), lr=1e-4)
for t in range(500):
    y_pred = model(x)
    loss = criterion(y_pred, y)
    optimizer.zero_grad()
    loss.backward()
```

Define new modules

Construct and train an instance of our model



import torch
from torch.autograd import Variable

```
class TwoLayerNet(torch.nn.Module):
    def __init__(self, D_in, H, D_out):
        super(TwoLayerNet, self).__init__()
        self.linear1 = torch.nn.Linear(D_in, H)
        self.linear2 = torch.nn.Linear(H, D_out)
```

```
def forward(self, x):
    h_relu = self.linearl(x).clamp(min=0)
    y_pred = self.linear2(h_relu)
    return y_pred
```

```
N, D_in, H, D_out = 64, 1000, 100, 10
```

```
x = Variable(torch.randn(N, D_in))
y = Variable(torch.randn(N, D_out), requires_grad=False)
```

```
model = TwoLayerNet(D_in, H, D_out)
```

```
criterion = torch.nn.MSELoss(size_average=False)
optimizer = torch.optim.SGD(model.parameters(), lr=1e-4)
for t in range(500):
    y_pred = model(x)
    loss = criterion(y_pred, y)
    optimizer.zero_grad()
    loss.backward()
    optimizer.step()
```

PyTorch: DataLoaders

A **DataLoader** wraps a **Dataset** and provides mini-batching, shuffling, multithreading, for you

When you need to load custom data, just write your own Dataset class import torch
from torch.utils import data

```
class Dataset(data.Dataset):
    'Characterizes a dataset for PyTorch'
    def __init__(self, list_IDs, labels):
        'Initialization'
        self.labels = labels
        self.list_IDs = list_IDs
```

```
def __len__(self):
    'Denotes the total number of samples'
    return len(self.list_IDs)
```

```
def __getitem__(self, index):
    'Generates one sample of data'
    # Select sample
    ID = self.list_IDs[index]
```

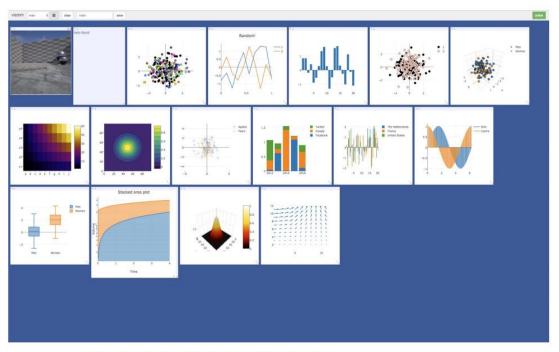
```
# Load data and get label
X = torch.load('data/' + ID + '.pt')
y = self.labels[ID]
```

PyTorch: DataLoaders

```
# Parameters
params = {'batch_size': 64,
          'shuffle': True,
          'num workers': 6}
max_epochs = 100
# Datasets
partition = # IDs
labels = # Labels
# Generators
training_set = Dataset(partition['train'], labels)
training generator = data.DataLoader(training set, **params)
validation_set = Dataset(partition['validation'], labels)
validation generator = data.DataLoader(validation set, **params)
# Loop over epochs
for epoch in range(max_epochs):
    # Training
    for local_batch, local_labels in training_generator:
        # Transfer to GPU
        local batch, local labels = local batch.to(device), local labels.to(device)
        # Model computations
        [...]
```

PyTorch: Visdom

Somewhat similar to TensorBoard: add logging to your code, then visualized in a browser



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Useful Resources in PS3

- Torch tensor and Numpy: <u>https://pytorch.org/tutorials/beginner/former_torchies/tensor_tutorial.html</u>
- DataLoader: <u>https://pytorch.org/docs/stable/data.html</u>
- Linear layer: <u>https://pytorch.org/docs/stable/generated/torch.nn.Linear.html</u>
- Sigmoid layer: <u>https://pytorch.org/docs/stable/generated/torch.nn.Sigmoid.html#torch.nn.Sigmoid</u>
- Cross Entropy Loss: <u>https://pytorch.org/docs/stable/generated/torch.nn.CrossEntropyLoss.html</u>
- Optimizer: <u>https://pytorch.org/docs/stable/optim.html</u>

Always check https://pytorch.org/docs/1.7.1/ official document for accurate up-to-date details!

Note: In PS3, you don't need to implement tensors on GPU (even if you do have access to GPU computing resources).





Thank you!